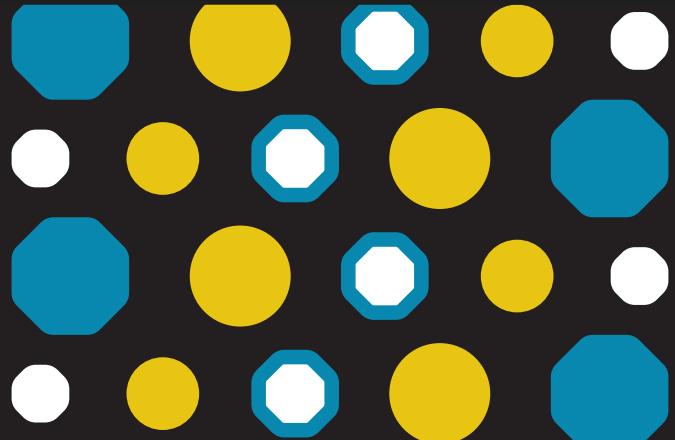


Perturbing Isoradial Triangulations

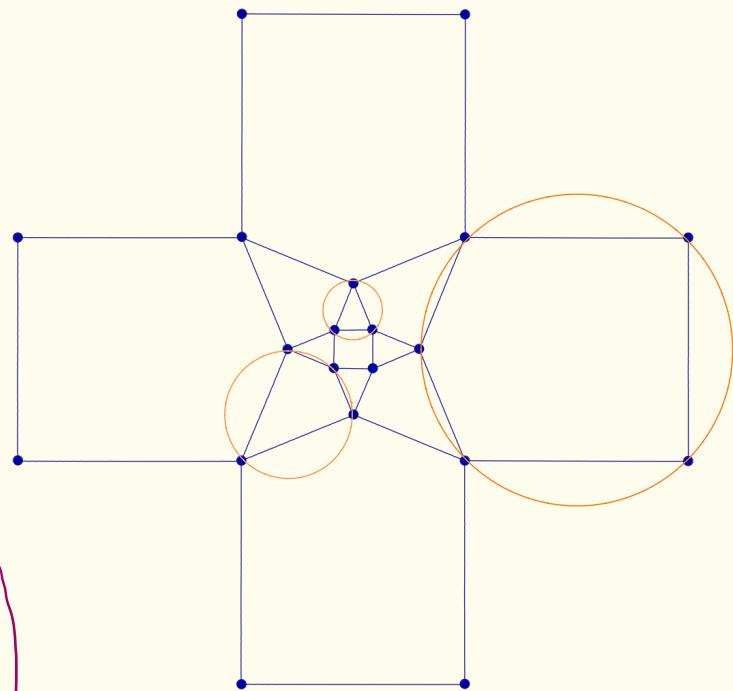
joint work with F. David (IPhT)
(Jussieu 2021)



(infinite) Delaunay Graph G

- planar graph with vertex embedding $z : V(G) \rightarrow \mathbb{C}$
- edges \mapsto straight line segments
- faces \mapsto cyclic polygons
- $\forall v \in V(G)$ and $\forall X \in F(G)$
 $z(v) \notin \text{int of circumdisk of } X$

$\overline{uv} \in E(G)$ iff $\exists w \neq u, v$ vertex
 such that $\forall w' \neq u, v, w$ vertex
 $\text{im} \left[z(u), z(v) ; z(w), z(w') \right] \in \mathbb{R}_{>0}$
 (cross-ratio)

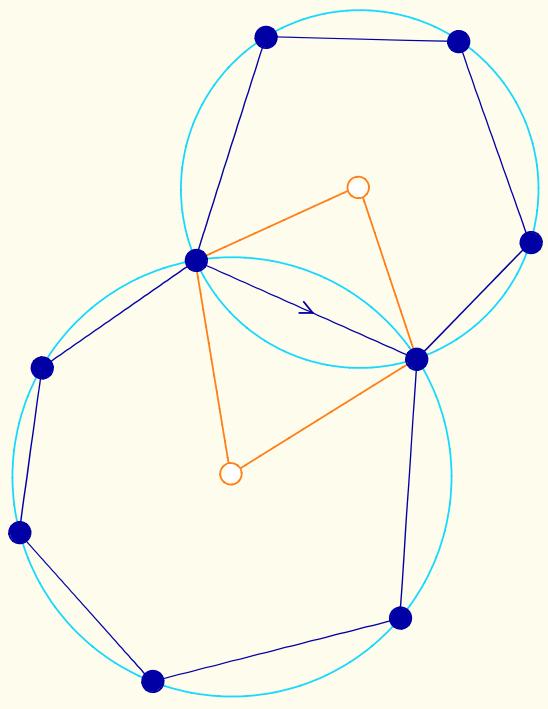


$V(G)$
 vertex set

$E(G)$
 edge set

$F(G)$
 face set

Notation / set-up :



for $u \in V(G)$, $z(u) \in \mathbb{C}$ coordinate

for an oriented edge \vec{uv} have

- north and south faces X_n, X_s
- circumcenters x_n, x_s
- circumradii R_n, R_s
- angles Θ_n, Θ_s
- conformal angle

$$\Theta(\vec{uv}) = \frac{1}{2} (\Theta_n(\vec{uv}) + \Theta_s(\vec{uv}))$$

$$\mathbb{C}^{V(G)} = \left\{ \phi : V(G) \rightarrow \mathbb{C} \right\}$$

$$\mathbb{C}^{F(G)} = \left\{ \phi : F(G) \rightarrow \mathbb{C} \right\}$$

vector spaces
complex-valued
functions

David-Eynard Kähler operator:

$$\mathcal{D} : \mathbb{C}^{V(G)} \rightarrow \mathbb{C}^{V(G)}, \phi \in \mathbb{C}^{V(G)}$$

$$\mathcal{D}\phi(u) = \sum_{\substack{\text{edges} \\ u \rightarrow v}} \omega_{\mathcal{D}}(\vec{uv}) [\phi(u) - \phi(v)]$$

$$\omega_{\mathcal{D}}(\vec{uv}) = \frac{1}{2} \left[\frac{\tan \theta_n(\vec{uv}) + i}{R_n^2} + \frac{\tan \theta_s(\vec{uv}) - i}{R_s^2} \right]$$

Remarks:

$$(1) \quad \overline{\mathcal{D}}^\top = \mathcal{D} \text{ (hermitian)}$$

$$(2) \quad \mathcal{D}_{11} = \mathcal{D}_z = \mathcal{D}_{\bar{z}} = 0$$

(three zero modes)

(3) Special Case:

if in addition G is
isoradial

(i.e. $\exists R_{cr} > 0$ such that
circumradius $R(f) = R_{cr}$
for each face $f \in F(G)$)

then $\theta_n(\vec{uv}) = \theta_s(\vec{uv})$ and so

$$\omega_{\mathcal{D}}(\vec{uv}) = R_{cr}^{-2} \tan \theta(\vec{uv})$$

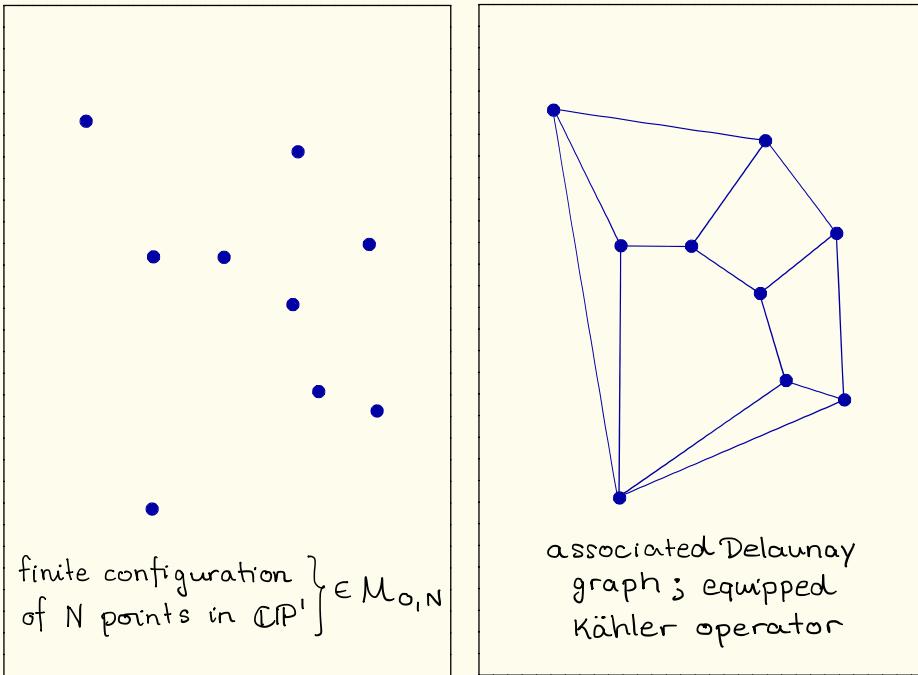
$$\text{i.e. } \mathcal{D} = R_{cr}^{-2} \Delta_{cr}$$

↑

Kenyon's critical Laplacian

voronoi construction

$\curvearrowright \text{SL}_2(\mathbb{C})$ -invariant



Get measure on

$$M_{0,N} \subset \underbrace{\mathbb{CP}^1 \times \dots \times \mathbb{CP}^1}_{N \text{ times}}$$

$$\frac{dz_1^2 \cdots dz_N^2 \det \mathcal{D}_{[4, N]}}{|z_1 - z_2|^2 \cdot |z_2 - z_3|^2 \cdots |z_1 - z_N|^2}$$

pullback of the
= Weil-Petersson
measure

(Charbonnier -
David-Eynard)

$M_{0,N} \simeq$ space of Delaunay graphs on
 \mathbb{CP}^1 with N labeled vertices

$\curvearrowleft \text{SL}_2(\mathbb{C})$ -action by
möbius trans.

$\curvearrowright \text{SL}_2(\mathbb{C})$ -equivariant isomorphism.

Basic Problem: study how $\det \mathcal{D}$ varies as the Delaunay graph G is perturbed/deformed.

Start with an infinite Delaunay graph G_{cr} which is isoradial and deform coordinate embedding z_{cr}

$$z_{\underline{\epsilon};l}(v) := z_{cr}(v) + \epsilon_1 F_{1;l}(v) + \dots + \epsilon_m F_{m;l}(v)$$

$\epsilon_1, \dots, \epsilon_m > 0$ independent deformation parameters

$l > 0$ scaling parameter

$F_1, \dots, F_m : \mathbb{C} \rightarrow \mathbb{C}$ smooth, compact supports

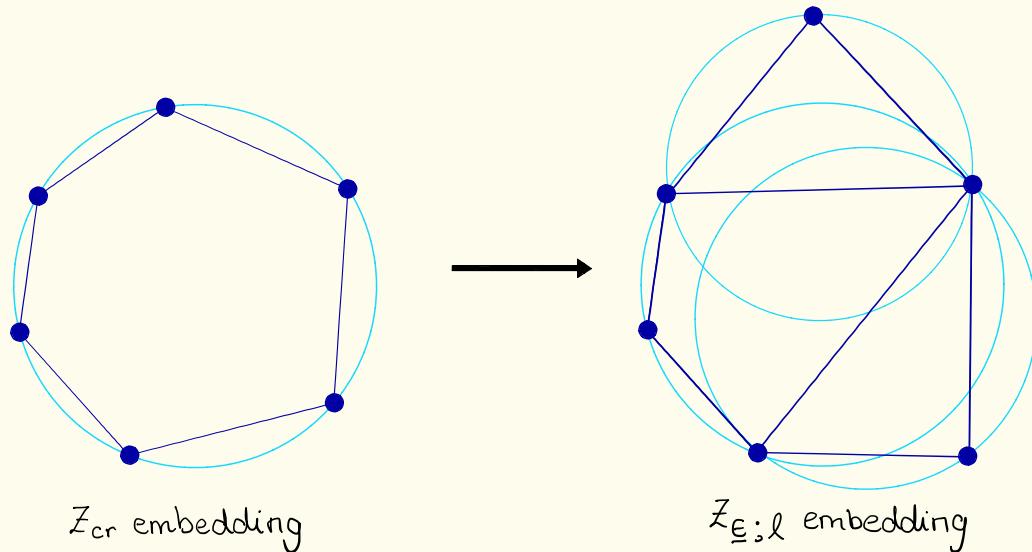
$\text{supp } F_i \cap \text{supp } F_j = \emptyset$ for all i, j

$$F_{i;l}(v) := l \cdot F_i \left(\frac{z_{cr}(v)}{l} \right)$$

We get Delaunay graph $G_{\underline{\epsilon};l}$
 vertex set $V(G_{\underline{\epsilon};l}) = V(G_{cr})$
 with Kähler operator $\mathcal{D}_{\underline{\epsilon},l}$

We want to compare $\mathcal{D}_{\underline{\epsilon};l}$ on $G_{\underline{\epsilon};l}$ and Δ_{cr} on G_{cr}

Difficulty: Delaunay constraints create/remove edges
and so $E(G_{\underline{\epsilon};l}) \neq E(G_{cr})$ and $F(G_{\underline{\epsilon};l}) \neq F(G_{cr})$



1st approach: find bounds $\hat{\epsilon}_i$ (depending on F_i) such that

stable
incidence
relations
within the
germ of the
deformation

- { ① $E(G_{cr}) \subseteq E(G_{\underline{\epsilon};l})$ whenever $0 \leq \epsilon_i < \hat{\epsilon}_i$
- ② $E(G_{\underline{\epsilon};l}) = E(G_{\underline{\epsilon}';l})$ whenever $0 < \epsilon_i, \epsilon_i' < \hat{\epsilon}_i$

This allows us to define a limit graph $G_{0^+;l}$ (^{depending}
_{on F_1, \dots, F_m})

vertex set $V(G_{0^+;l}) = V(G_{cr})$
 edge set $E(G_{0^+;l}) \supseteq E(G_{cr})$
 and embedding $Z_{0^+;l} = Z_{cr}$

} in general $G_{0^+;l}$ is
isoradial and
"weakly" Delaunay

Note: if G_{cr} is a triangulation then so is $G_{\underline{\epsilon};l}$

$$\text{furthermore } E(G_{\underline{\epsilon};l}) = E(G_{cr})$$

$$F(G_{\underline{\epsilon};l}) = F(G_{cr})$$

$$\text{therefore } G_{0^+;l} = G_{cr}.$$

2nd approach: do not require that $E(G_{cr}) \subseteq E(G_{\underline{\epsilon}}; \ell)$ but bound deformation parameters so that the growth of $R_{\underline{\epsilon}}(x)$ is bounded as $\underline{\epsilon}$ varies
 \rightarrow allows us to estimate $\delta \mathcal{D} = \int_0^{\underline{\epsilon}} d\underline{\epsilon} \mathcal{D}'(\underline{\epsilon})$

Proposition: ($m=1$) let $M_1 = \sup_{z \in \mathbb{C}} \max \left\{ |\partial F(z)|, |\bar{\partial} F(z)| \right\}$
 $M_2 = \sup_{z \in \mathbb{C}} \max \left\{ |\partial^2 F(z)|, |\partial \bar{\partial} F(z)|, |\bar{\partial}^2 F(z)| \right\}$

$$\epsilon_{\max} = \frac{1}{2M_1} \left(1 - \left(1 + \frac{M_1}{R_{cr} M_2} \right)^{-\frac{1}{4}} \right)$$

then $\bar{R}_-(\epsilon) \leq R_\epsilon(x) \leq \bar{R}_+(\epsilon) \quad \forall x \in F(G_{cr}) \quad \forall 0 \leq \epsilon < \epsilon_{\max}$

$$\bar{R}_-(\epsilon) = \frac{R_{cr} (1 - 2M_1 \epsilon)^2}{1 + \frac{8M_2 R_{cr}}{M_1} \log \left(\frac{1}{1 - 2M_1 \epsilon} \right)}$$

$$\bar{R}_+(\epsilon) = \frac{R_{cr}}{\left(1 + \frac{M_2 R_{cr}}{M_1} \right) (1 - 2M_1 \epsilon)^2 - \frac{M_2 R_{cr}}{M_1} (1 - 2M_1 \epsilon)^{-2}}$$

set $\delta \mathcal{D} = \mathcal{D}_{\epsilon, l} - R_{cr}^{-2} \Delta_{cr}$ and then formally expand

$$\underbrace{\log \det \mathcal{D} - \log \det \Delta_{cr}}_{\text{variation } \delta \log \det \mathcal{D}} = \underbrace{R_{cr}^2 \operatorname{tr} [\delta \mathcal{D} \cdot \Delta_{cr}^{-1}] - \frac{1}{2} R_{cr}^4 \operatorname{tr} [\delta \mathcal{D} \cdot \Delta_{cr}^{-1}]^2}_{\text{each trace term} < \infty} + \dots$$

where Δ_{cr}^{-1} is the Green's function of Δ_{cr} characterised by

$$(1) \quad \Delta_{cr} \Delta_{cr}^{-1} = \mathbb{1} \quad \begin{array}{l} \text{(means that} \\ \text{$u \mapsto [\Delta_{cr}^{-1}]_{uv}$} \\ \text{is harmonic)} \end{array}$$

$$(2) \quad [\Delta_{cr}^{-1}]_{uv} = O(\log |z_u - z_v|)$$

for \$u, v \in V(T)\$, \$|z_u - z_v| \gg 0\$

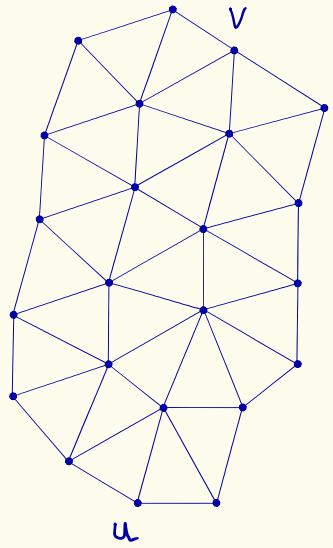
$$(3) \quad [\Delta_{cr}^{-1}]_{u,u} = 0$$

$$[\Delta_{cr}^{-1}]_{uv} = -\frac{1}{2\pi} \left(\underbrace{\log 2D + \gamma_{\text{Euler}}}_{\text{Kenyon 2002}} + \underbrace{\frac{\operatorname{re}[P_3(u,v)]}{6D^3}}_{\text{refinement}} + O(D^{-4}) \right)$$

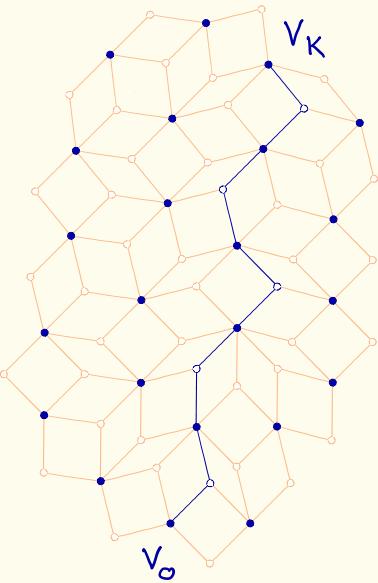
Asymptotics:

DS 2021

here $D = |z_{cr}(u) - z_{cr}(v)|$
and $|P_3(u,v)| \leq 3D$



isoradial Delaunay
graph G_{cr}



bipartite rhombic
graph G_{cr}^\diamond

v_0, \dots, v_K path in G_{cr}^\diamond
with $v_0 = u$ and $v_K = v$

$$R_{cr} e^{i\alpha_j} = Z_{cr}(v_j) - Z_{cr}(v_{j-1})$$

$$P_3(u, v) :=$$

$$R_{cr} \left(e^{3i\alpha_1} + \dots + e^{3i\alpha_K} \right)$$

independent of path

For simplicity assume G_{cr} is a triangulation then

Thm (D,S) let $m=2$ (i.e. bilocal perturbation)

then the $\epsilon_1 \epsilon_2$ -crossterm of $R_{cr}^4 \operatorname{tr} [\delta \mathcal{D} \cdot \Delta_{cr}^{-1}]^2$ is

$$-\frac{2}{\pi^2} \sum_{\text{triangles } (X_1, X_2)} A(X_1) A(X_2) \operatorname{re} \left[\frac{\bar{\nabla} F_{1;l}(X_1) \bar{\nabla} F_{2;l}(X_2)}{(x_1 - x_2)^4} \right] + O(D_l^{-5})$$

(X_1, X_2)

where x_i is the center of X_i

$D_l = \operatorname{dist}(\Omega_1(l), \Omega_2(l))$ and

$$\Omega_i(l) = \left\{ z \in \mathbb{C} \mid z/l \in \operatorname{supp} F_i \right\}$$

$$\nabla, \bar{\nabla} : \mathbb{C}^{V(G)} \longrightarrow \mathbb{C}^{F(G)}$$

discrete derivatives

$l \rightarrow \infty$

scaling limit

$$\boxed{-\frac{2}{\pi^2} \iint_{\Omega_1 \times \Omega_2} dx_1^z dx_2^z \operatorname{re} \left[\frac{\bar{\partial} F_1(x_1) \bar{\partial} F_2(x_2)}{(x_1 - x_2)^4} \right]}$$

$$\nabla \phi(X) = \frac{-1}{4i A(X)} \det \begin{pmatrix} 1 & 1 & 1 \\ \bar{z}(v_1) & \bar{z}(v_2) & \bar{z}(v_3) \\ \phi(v_1) & \phi(v_2) & \phi(v_3) \end{pmatrix}$$

v_1, v_2, v_3 vertices of X in counter-clockwise order

Proof involves :

- asymptotic expansion $[\Delta_{cr}^{-1}]_{uv} = -\frac{1}{2\pi} \left(\log 2D + \gamma_{Euler} + \frac{\operatorname{re}[P_3(u,v)]}{6D^3} + O(D^{-4}) \right)$
 - operator factorisation $\mathcal{D} = 4 \bar{\nabla}^T A R^{-2} \nabla$ where
 $A, R : \mathbb{C}^{F(G)} \rightarrow \mathbb{C}^{F(G)}$ diagonal operators $A\phi(x) = A(x)\phi(x)$, $R\phi(x) = R(x)\phi(x)$
- note : Beltrami-Laplace operator $\Delta = 4 \operatorname{re} [\bar{\nabla}^T A \nabla]$

discrete stress energy tensor $T_{\mathcal{D}}$:

$$R_{cr}^2 \operatorname{tr} [\delta \mathcal{D} \cdot \Delta_{cr}^{-1}] = \begin{cases} -4 \operatorname{tr} \left[\bar{\nabla}^T A (\nabla F + \bar{\nabla} \bar{F} + C \bar{\nabla} F + \bar{C} \nabla \bar{F}) \nabla \cdot \Delta_{cr}^{-1} \right] & (m=1) \\ -4 \operatorname{tr} [\nabla^T A \bar{\nabla} F \nabla \cdot \Delta_{cr}^{-1}] - 4 \operatorname{tr} [\bar{\nabla}^T A \nabla \bar{F} \bar{\nabla} \cdot \Delta_{cr}^{-1}] + O(\epsilon^2) \end{cases}$$

$$= -\frac{1}{\pi} \sum_{x \in F(G_{cr})} A(x) \operatorname{re} \left[\bar{\nabla} F(x) \langle T_{\mathcal{D}}(x) \rangle \right] + \frac{1}{2} \sum_{x \in F(G_{cr})} A(x) \langle T_{\mathcal{D}}^{z\bar{z}}(x) \rangle \operatorname{re} [\nabla F(x)] + O(\epsilon^2)$$

↑
x ∈ F(G_{cr})
expectation values

$$\left. \begin{aligned} T_{\mathcal{D}}(x) &= -\frac{\pi}{2} T_{\mathcal{D}}^{\bar{z}\bar{z}}(x) = -4\pi R^{-2}(x) \left[\nabla\phi(x)\nabla\bar{\phi}(x) + C(x)\bar{\nabla}\bar{\phi}(x)\bar{\nabla}\phi(x) \right] \\ \bar{T}_{\mathcal{D}}(x) &= -\frac{\pi}{2} T_{\mathcal{D}}^{zz}(x) = -4\pi R^{-2}(x) \left[\bar{\nabla}\phi(x)\bar{\nabla}\bar{\phi}(x) + \bar{C}(x)\bar{\nabla}\phi(x)\nabla\bar{\phi}(x) \right] \\ T_{\mathcal{D}}^{\bar{z}\bar{z}}(x) &= 8R^{-2}(x)\bar{\nabla}\phi\nabla\bar{\phi} \end{aligned} \right\} \text{components of the stress energy tensor } T_{\mathcal{D}}$$

where $\langle A \rangle = Z_{\epsilon; \ell}^{-1} \int \mathcal{D}[\phi] A[\phi] e^{-\bar{\phi} \cdot \mathcal{D}_{\epsilon; \ell} \phi}$

$$\begin{aligned} Z_{\epsilon; \ell} &= \int \mathcal{D}[\phi] e^{-\bar{\phi} \cdot \mathcal{D}_{\epsilon; \ell} \phi} \\ &= \det^{-\frac{1}{2}} \mathcal{D}_{\epsilon; \ell} \end{aligned}$$

and we formally compute in the language of functional integrals using Wick's theorem :

$$[\mathcal{D}_{\epsilon; \ell}]_{uv}^{-1} = \langle \phi(u) \bar{\phi}(v) \rangle$$

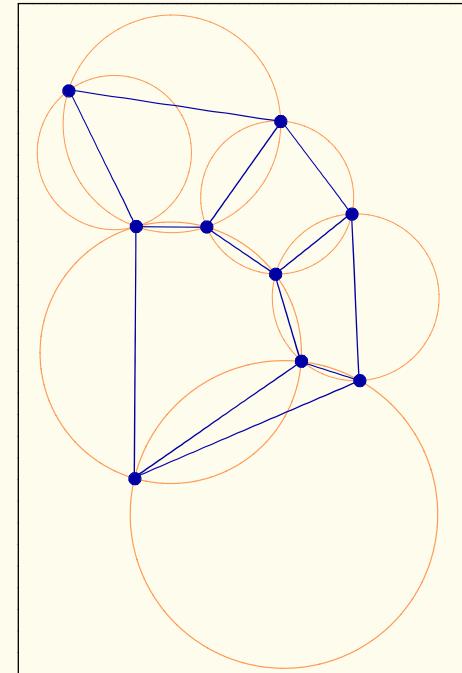
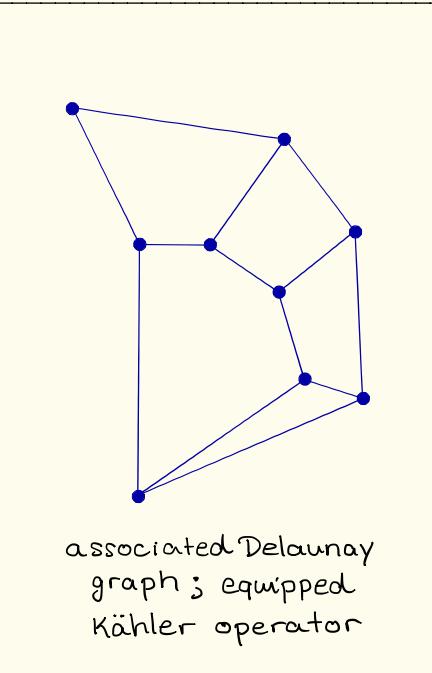
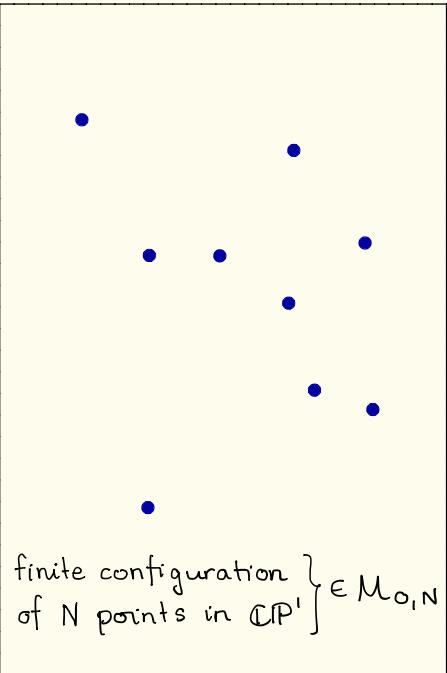
etc...

we have a similar formula for $R_{cr}^4 \text{tr} [\delta \mathcal{D} \cdot \Delta_{cr}^{-1}]^2$ in terms of components of the stress energy tensor.

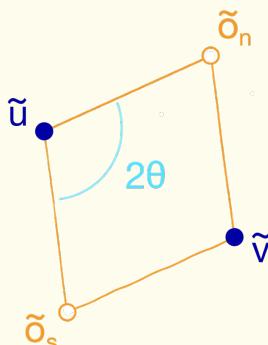
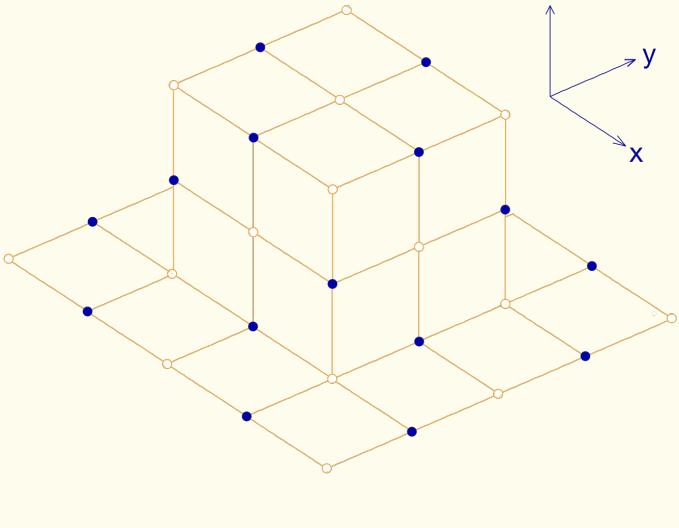
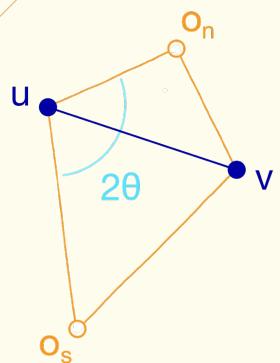
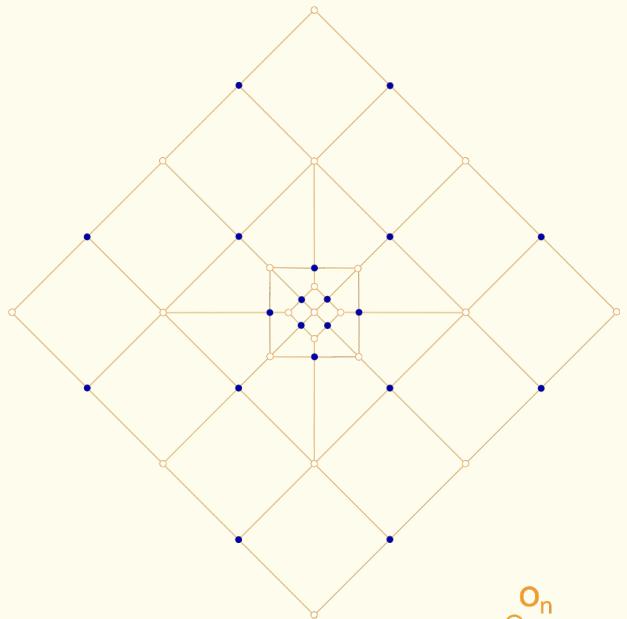
voronoi
construction

CDE
construction

Teichmüller
space $T_{0,N}$
N marked
points in \mathbb{CP}^2



each circumdisk $D(f)$ given
Beltrami - Klein metric, then
restrict to face $f \in F(G)$
and stitch metrics together



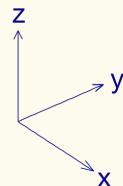
$$\sum_{e \in \partial x} \theta(e) = \frac{\pi}{2}$$

"flatness"

$$\sum_{v \in \partial e} \theta(e) = \pi$$

•

always



def a Delaunay triangulation T is isoradial if all circumradii are equal; $R_f = R_{cr} > 0 \quad \forall f \in F(T)$

in this case $\Delta = \mathcal{D} = \Delta_{\text{conf}}$
 (and $R_{cr}=1$) "critical laplacian" Δ_{cr}

Green's function Δ_{cr}^{-1} (studied by R. Kenyon '02)
 characterised by properties

$$(1) \Delta_{cr} \Delta_{cr}^{-1} = \mathbb{1} \quad \begin{array}{l} \text{(means that} \\ u \mapsto [\Delta_{cr}^{-1}]_{uv} \end{array} \text{is harmonic}$$

$$(2) [\Delta_{cr}^{-1}]_{uv} = O(\log |z_u - z_v|)$$

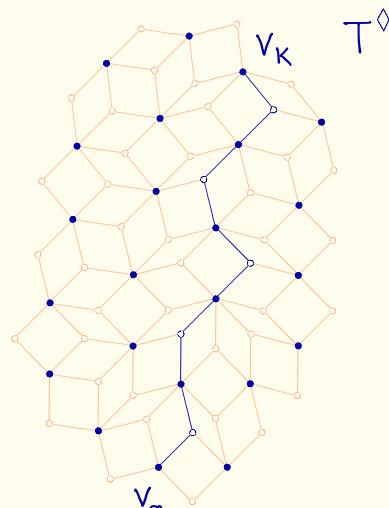
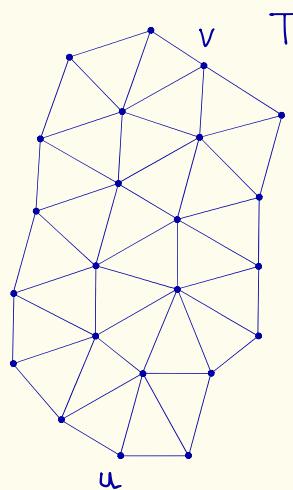
for $u, v \in V(T), |z_u - z_v| \gg 0$

$$(3) [\Delta_{cr}^{-1}]_{u,u} = 0$$

by [Kenyon 2002]

$$(1) [\Delta_{cr}^{-1}]_{uv} = \frac{1}{2\pi} \operatorname{re} \int_0^1 \frac{dt}{t} (E_{\underline{\theta}}(-t) - 1)$$

$$\text{where } E_{\underline{\theta}}(z) = \prod_{j=1}^K \frac{z + e^{i\theta_j}}{z - e^{i\theta_j}}$$



$v_0 = u$ and $v_K = v$

$$e^{i\theta_j} = z(v_j) - z(v_{j-1})$$

rhombic graph
 v_0, \dots, v_K path